page	Says	Should say
page 11 - eq. 2.5	$= A_{11}(\rho(t))\ z(t) + A_{22}(\rho(t))\ w(t)$	$= A_{21}(\rho(t))\ z(t) + A_{22}(\rho(t))\ w(t)$
page 12 - eq. 2.8	$[\frac{\partial A_{11}}{\partial z}\ z + A_{11} + \frac{\partial A_{21}}{\partial z}\ w + \frac{\partial B_1}{\partial z}\ u + \frac{\partial E_1}{\partial z}\ p]\Big\vert_{eq}\ \delta_z$	$[\frac{\partial A_{11}}{\partial z}\ z + A_{11} + \frac{\partial A_{12}}{\partial z}\ w + \frac{\partial B_1}{\partial z}\ u + \frac{\partial E_1}{\partial z}\ p]\Big\vert_{eq}\ \delta_z$
page 12 - eq. 2.8	$[\frac{\partial A_{11}}{\partial p}\ z + \frac{\partial A_{12}}{\partial p}\ w + \frac{\partial B_1}{\partial z}\ u + \frac{\partial E_1}{\partial p}\ p + E_1]\Big\vert_{eq}\ \delta_p$	$[\frac{\partial A_{11}}{\partial p}\ z + \frac{\partial A_{12}}{\partial p}\ w + \frac{\partial B_1}{\partial p}\ u + \frac{\partial E_1}{\partial p}\ p + E_1]\Big\vert_{eq}\ \delta_p$
page 13 - eq. 2.16	$e_1 = \frac{\partial A_{11}}{\partial p}\ z + \frac{\partial A_{12}}{\partial p}\ w + \frac{\partial B_1}{\partial z}\ u + \frac{\partial E_1}{\partial p}\ p + E_1$	$e_1 = \frac{\partial A_{11}}{\partial p}\ z + \frac{\partial A_{12}}{\partial p}\ w + \frac{\partial B_1}{\partial p}\ u + \frac{\partial E_1}{\partial p}\ p + E_1$
page 13 - eq. 2.17	$e_2 = \frac{\partial A_{21}}{\partial p}\ z + \frac{\partial A_{22}}{\partial p}\ w + \frac{\partial B_2}{\partial z}\ u + \frac{\partial E_2}{\partial p}\ p + E_1$	$e_2 = \frac{\partial A_{21}}{\partial p}\ z + \frac{\partial A_{22}}{\partial p}\ w + \frac{\partial B_2}{\partial p}\ u + \frac{\partial E_2}{\partial p}\ p + E_1$
page 14 - eq. 2.19	$0 = A_{11}\ z + A_{22}\ w_{eq}(z,p) + B_2\ u_{eq}(z,p) + E_2\ p$	$0 = A_{21}\ z + A_{22}\ w_{eq}(z,p) + B_2\ u_{eq}(z,p) + E_2\ p$
page 26 - eq. 2.46	$\begin{bmatrix}\dot\eta_z - \dot z_{trim}\\ \dot\eta_w - \dot w_{trim}\end{bmatrix} = \begin{bmatrix}A_{11}(\eta_z + z_{trim}) & A_{12}(\eta_z + z_{trim})\\ A_{21}(\eta_z + z_{trim}) & A_{22}(\eta_z + z_{trim})\end{bmatrix}\begin{bmatrix}\eta_z\\ \eta_w\end{bmatrix}$	$\begin{bmatrix}\dot\eta_z + \dot z_{trim}\\ \dot\eta_w + \dot w_{trim}\end{bmatrix} = \begin{bmatrix}A_{11}(\eta_z + z_{trim}) & A_{12}(\eta_z + z_{trim})\\ A_{21}(\eta_z + z_{trim}) & A_{22}(\eta_z + z_{trim})\end{bmatrix}\begin{bmatrix}\eta_z\\ \eta_w\end{bmatrix} +$
page 93 - eq. 4.45	$\begin{bmatrix}0\\ 0\\ 0\\ q - q_{trim}(\rho)\\ \theta - \theta_{trim}(\rho)\end{bmatrix}$	$\begin{bmatrix}\alpha - \alpha_{trim}(\rho)\\ V_{TAS} - V_{TAS_{trim}}(\rho)\\ he - he_{trim}(\rho)\\ q - q_{trim}(\rho)\\ \theta - \theta_{trim}(\rho)\end{bmatrix}$

Table 1: Errata as of 11-Dec-2003.

page	**Addendum**
page xii	include: $(x, y, z)_{cg}$ – center gravity position X,Y,Z-axis – (meters).
page xii	include: $(\bar{x}, \bar{y}, \bar{z})_{cg}$ – corrected center gravity position = $(x, y, z)_{ref} - (x, y, z)_{cg}$ – (meters).
page xii	include: $(x, y, z)_{ref}$ – reference center gravity position = $(31.75, 0.0, 0.0)$ – (meters).
page xiv	include: ρ – scheduling parameters vector – (—).
page 93	include: It is noted that since the scheduling vector is $\rho = (\alpha, V_{TAS}, he)$ the equivalent deviations are zero, e.g. $[\ \alpha - \alpha_{trim}(\rho) = \alpha - \alpha = 0\ ]$.

Table 2: Addendum as of 11-Dec-2003.